

GPCorrelation

De Wiki

Aller à : [navigation](#), [rechercher](#)
[GPCorrelation](#)

This widget allows to manage "**pseudo correlation**" or **covariance** matrices.

Why "**pseudo correlation**" ? In fact a real correlation matrix has its diagonal only with values of "1", the sigma values being given independantly. Here, we will consider a "**pseudo correlation**" with the diagonal filled with these sigma values !

Sommaire

- [1 How to call it](#)
- [2 Display](#)
- [3 How to use it](#)
- [4 How it is stored](#)

How to call it

For using the [GPCorrelation](#) class, the developer has only to create such an object as is:

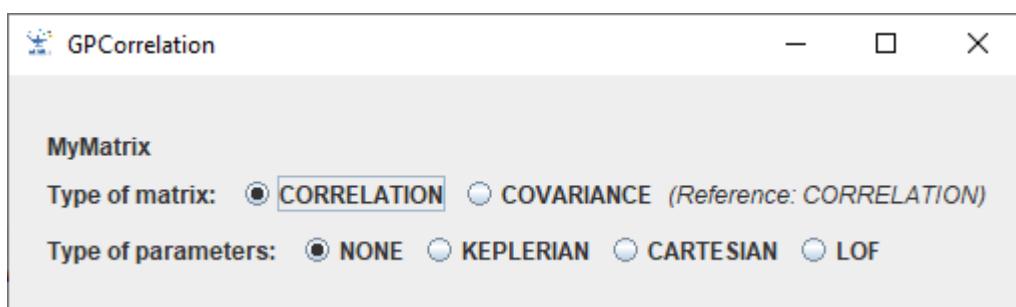
```
gpCor = new GPCorrelation();
```

or:

```
gpCor = new GPCorrelation("widgetId", "MyMatrix");
```

Display

We will get:



By selecting the type of parameters, we may enter data for pseudo correlation/covariance matrices for Keplerian/Cartesian/**LOF** cartesians parameters. The different displays will be:

- In case of Keplerian parameters:

MyMatrix

Type of matrix: CORRELATION COVARIANCE (Reference: CORRELATION)

Type of parameters: * NONE KEPLERIAN CARTESIAN LOF

Sigma a					
Rho a/e	Sigma e				
Rho a/i	Rho e/i	Sigma i			
Rho a/w	Rho e/w	Rho i/w	Sigma w		
Rho a/Raan	Rho e/Raan	Rho i/Raan	Rho w/Raan	Sigma Raan	
Rho a/v	Rho e/v	Rho i/v	Rho w/v	Rho Raan/v	Sigma v
					0.0 deg

- In case of cartesian parameters:

MyMatrix

Type of matrix: CORRELATION COVARIANCE (Reference: CORRELATION)

Type of parameters: * NONE KEPLERIAN CARTESIAN LOF

Sigma x					
Rho x/y	Sigma y				
Rho x/z	Rho y/z	Sigma z			
Rho x/vx	Rho y/vx	Rho z/vx	Sigma vx		
Rho x/vy	Rho y/vy	Rho z/vy	Rho vx/vy	Sigma vy	
Rho x/vz	Rho y/vz	Rho z/vz	Rho vx/vz	Rho vy/vz	Sigma vz
					0.0 m/s

- In case of LOF cartesian parameters:

MyMatrix

Type of matrix: CORRELATION COVARIANCE (Reference: CORRELATION)

Type of parameters: * NONE KEPLERIAN CARTESIAN LOF

LOF types:

Absolute velocity:

Sigma x					
Rho x/y	Sigma y				
Rho x/z	Rho y/z	Sigma z			
Rho x/vx	Rho y/vx	Rho z/vx	Sigma vx		
Rho x/vy	Rho y/vy	Rho z/vy	Rho vx/vy	Sigma vy	
Rho x/vz	Rho y/vz	Rho z/vz	Rho vx/vz	Rho vy/vz	Sigma vz
					0.0 m/s

So we may have a covariance matrix rather than a pseudo correlation one:

GPCorrelation

MyMatrix

Type of matrix: CORRELATION COVARIANCE (Reference: COVARIANCE)

Type of parameters: NONE KEPLERIAN CARTESIAN LOF

LOF types: QSW

Absolute velocity:

Sigma**2 x	0.0 <input type="text" value="m^2"/>	Sigma**2 y	0.0 <input type="text" value="m^2"/>	Sigma**2 z	0.0 <input type="text" value="m^2"/>	Sigma**2 vx	0.0 <input type="text" value="m^2/s^2"/>	Sigma**2 vy	0.0 <input type="text" value="m^2/s^2"/>	Sigma**2 vz	0.0 <input type="text" value="m^2/s^2"/>
Rho Sigma Sigma x/y	0.0 <input type="text" value="m^2"/>	Rho Sigma Sigma y/z	0.0 <input type="text" value="m^2"/>	Rho Sigma Sigma z/x	0.0 <input type="text" value="m^2"/>	Rho Sigma Sigma y/vx	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma z/vy	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma vx/vy	0.0 <input type="text" value="m^2/s^2"/>
Rho Sigma Sigma x/vx	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma y/vy	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma z/vz	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma v/vz	0.0 <input type="text" value="m^2/s^2"/>	Rho Sigma Sigma vy/vz	0.0 <input type="text" value="m^2/s^2"/>	Rho Sigma Sigma vx/vz	0.0 <input type="text" value="m^2/s^2"/>
Rho Sigma Sigma x/vy	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma y/vz	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma z/vx	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma vx/vx	0.0 <input type="text" value="m^2/s^2"/>	Rho Sigma Sigma vy/vy	0.0 <input type="text" value="m^2/s^2"/>	Rho Sigma Sigma vx/vy	0.0 <input type="text" value="m^2/s^2"/>
Rho Sigma Sigma x/vz	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma y/vz	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma z/vy	0.0 <input type="text" value="m.m/s"/>	Rho Sigma Sigma vx/vy	0.0 <input type="text" value="m^2/s^2"/>	Rho Sigma Sigma vy/vz	0.0 <input type="text" value="m^2/s^2"/>	Rho Sigma Sigma vx/vz	0.0 <input type="text" value="m^2/s^2"/>

If the initial pseudo correlation (resp. covariance) matrix is not null, a specific pop-up window will appear to ask for the type of conversion. A bit as for the [GPOrbit](#) widget, it will be possible to do this conversion between pseudo correlation and covariance matrices (but not between the different type of parameters) using a kind of “pivot” notion.

Change matrix type

What do you want to do ?

- Convert initial data (CORRELATION) but keep initial data as reference
- Convert initial data (CORRELATION) and use them them as reference
- Change type and reset data
- Cancel operation

GPCorrelation

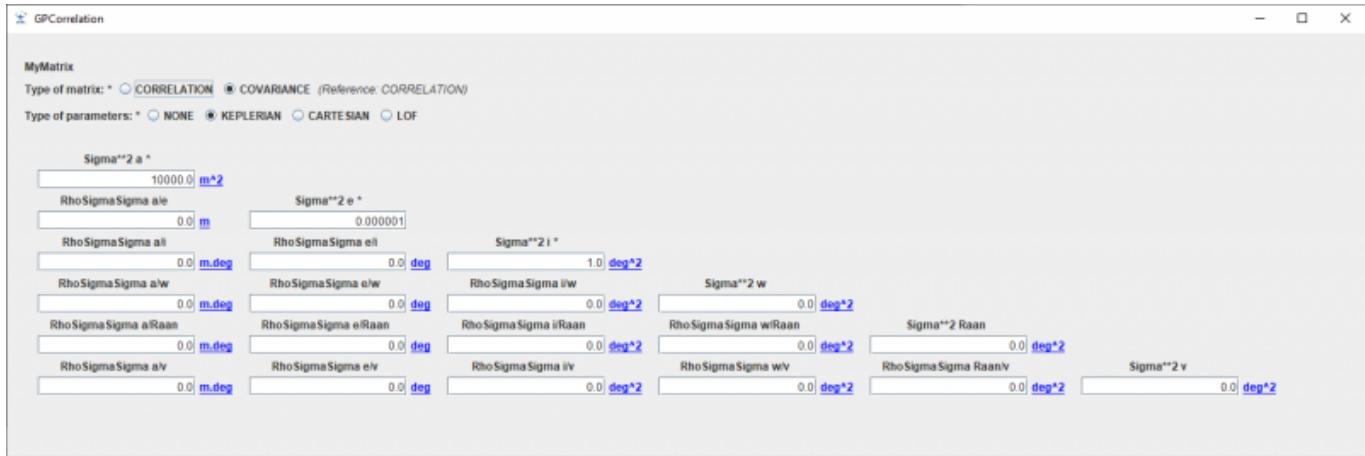
MyMatrix

Type of matrix: CORRELATION COVARIANCE (Reference: CORRELATION)

Type of parameters: NONE KEPLERIAN CARTESIAN LOF

Sigma a *	100.0 <input type="text" value="m"/>	Sigma e *	0.001 <input type="text"/>	Sigma i *	1.0 <input type="text" value="deg"/>	Sigma w	0.0 <input type="text" value="deg"/>	Sigma Raan	0.0 <input type="text" value="deg"/>	Sigma v	0.0 <input type="text" value="deg"/>
Rho ale	0.0 <input type="text"/>	Rho ell	0.0 <input type="text"/>	Rho ilw	0.0 <input type="text"/>	Rho wiRaan	0.0 <input type="text"/>	Rho Raanv	0.0 <input type="text" value="deg"/>	Rho v	0.0 <input type="text" value="deg"/>
Rho all	0.0 <input type="text"/>	Rho eli	0.0 <input type="text"/>	Rho ilv	0.0 <input type="text"/>	Rho wRaan	0.0 <input type="text"/>	Rho Raanl	0.0 <input type="text" value="deg"/>	Rho v	0.0 <input type="text" value="deg"/>
Rho a/w	0.0 <input type="text"/>	Rho e/w	0.0 <input type="text"/>	Rho ilw	0.0 <input type="text"/>	Rho wiRaan	0.0 <input type="text"/>	Rho Raanv	0.0 <input type="text" value="deg"/>	Rho v	0.0 <input type="text" value="deg"/>
Rho a/Raan	0.0 <input type="text"/>	Rho e/Raan	0.0 <input type="text"/>	Rho ilRaan	0.0 <input type="text"/>	Rho w/Raan	0.0 <input type="text"/>	Rho Raanl	0.0 <input type="text" value="deg"/>	Rho v	0.0 <input type="text" value="deg"/>
Rho alv	0.0 <input type="text"/>	Rho e/v	0.0 <input type="text"/>	Rho iv	0.0 <input type="text"/>	Rho w/v	0.0 <input type="text"/>	Rho Raanv	0.0 <input type="text" value="deg"/>	Rho v	0.0 <input type="text" value="deg"/>

=>



How to use it

There are no exactly corresponding correlation/covariance matrices inside [PATRIUS](#) but [GENOPUS](#) gives some utility classes and methods to use them.

In the examples below, we can recover the widget data inside [PATRIUS](#) RealMatrix or Realvector objects.

```
final GPCorrelationData data = gpCor.getGpCorrelationData();

final RealMatrix corMat = data.getCorrelationMatrix();
final RealMatrix covMat = data.getCovarianceMatrix();
final RealMatrix sqrtRootcovMat = data.getSqrtCovarianceMatrix();
final RealVector sigma = data.getSigma();
```

We have also the possibility to use these utility methods:

```
final RealMatrix mat1 = GPCorrelationUtils.corToCov(sigma, corMat);
final RealMatrix mat2 = GPCorrelationUtils.pseudoCorToCov(corMat);
final RealMatrix mat3 = GPCorrelationUtils.covToPseudoCor(covMat);
```

How it is stored

Here is an example of the [XML](#) format:

```
<!--Type of matrix:-->
<String name="matrixType">CORRELATION</String>
<!--Type of parameters:-->
<String name="type">LOF</String>
<!--LOF types:-->
<String name="lofType">LVLH</String>
<!--Absolute velocity:-->
<Boolean name="velocityType">true</Boolean>
<Real name="Sigma_x" unit="m">1.0E1</Real>
<Real name="Rho_x/y">5.0E-1</Real>
<Real name="Rho_x/z">0.0E0</Real>
```

```
<Real name="Rho_x/vx">0.0E0</Real>
<Real name="Rho_x/vy">0.0E0</Real>
<Real name="Rho_x/vz">0.0E0</Real>
<Real name="Sigma_y" unit="m">2.0E4</Real>
<Real name="Rho_y/z">0.0E0</Real>
<Real name="Rho_y/vx">0.0E0</Real>
<Real name="Rho_y/vy">0.0E0</Real>
<Real name="Rho_y/vz">0.0E0</Real>
<Real name="Sigma_z" unit="m">3.0E4</Real>
<Real name="Rho_z/vx">0.0E0</Real>
<Real name="Rho_z/vy">0.0E0</Real>
<Real name="Rho_z/vz">0.0E0</Real>
<Real name="Sigma_vx" unit="m/s">1.0E2</Real>
<Real name="Rho_vx/vy">0.0E0</Real>
<Real name="Rho_vx/vz">0.0E0</Real>
<Real name="Sigma_vy" unit="m/s">2.0E2</Real>
<Real name="Rho_vy/vz">0.0E0</Real>
<Real name="Sigma_vz" unit="m/s">3.0E2</Real>
```

Récupérée de « <http://genopus.cnes.fr/index.php?title=GPCorrelation&oldid=570> »

Menu de navigation

Outils personnels

- [18.223.159.195](#)
- [Discussion avec cette adresse IP](#)
- [Créer un compte](#)
- [Se connecter](#)

Espaces de noms

- [Page](#)
- [Discussion](#)

Variantes

Affichages

- [Lire](#)
- [Voir le texte source](#)
- [Historique](#)
- [Exporter en PDF](#)

Plus

Rechercher

	Rechercher	Lire
--	------------	------

GENOPUS

- [Welcome](#)
- [Quick Start](#)
- [News](#)

User Manual

- [BasicPrinciples](#)
- [GPAbsoluteDate](#)
- [GPOrbit](#)
- [GPFramesConfiguration](#)
- [GPVehicle](#)
- [GPForceModels](#)
- [GPManeuverSequence](#)
- [GPAltitudeSequence](#)
- [GPIntegrator](#)
- [GPAxisCoordinates](#)
- [GPGeodeticPoint](#)
- [GPOneAxisEllipsoid](#)
- [GPRotation](#)
- [GPConstants](#)
- [Events](#)
- [GPCorrelation](#)

Evolutions

- [Main differences between V2.4.1 and V2.4.2](#)
- [Main differences between V2.3.3 and V2.4.1](#)
- [Main differences between V2.2.1 and V2.3.3](#)
- [Main differences between V2.2 and V2.2.1](#)
- [Main differences between V2.1.1 and V2.2](#)
- [Main differences between V2.1 and V2.1.1](#)
- [Main differences between V2.0.1 and V2.1](#)
- [Main differences between V2.0 and V2.0.1](#)
- [Main differences between V1.3.1 and V2.0](#)
- [Main differences between V1.3 and V1.3.1](#)
- [Main differences between V1.2.1 and V1.3](#)

Training

- [Make your own propagator tool!](#)
- [Tutorials package for V2.4.1](#)
- [Tutorials package for V2.3.3](#)
- [Tutorials package for V2.2](#)
- [Tutorials package for V2.1.1](#)
- [Tutorials package for V2.0 and V2.0.1](#)
- [Tutorials package for V1.3 and V1.3.1](#)
- [Training slides](#)

Links

- [CNES freeware server](#)

Outils

- [Pages liées](#)
- [Suivi des pages liées](#)
- [Pages spéciales](#)
- [Adresse de cette version](#)
- [Information sur la page](#)
- [Citer cette page](#)
- Dernière modification de cette page le 13 décembre 2021 à 16:38.
- [Politique de confidentialité](#)
- [À propos de Wiki](#)
- [Avertissements](#)
-  Powered By MediaWiki